Building for RISC OS, Online

and what makes it tick

Gerph, November 2020



0. Introduction

November 2020



Introduction

How I'll do this talk

- Lots of technology, some of which may be alien to you.
- The talk is split into 5 sections, with a chance for some questions between them.
- Slides will be available at the end, together with some other resources.
- I'll take questions at the end for as long as people want.



Introduction

What we'll talk about

- 1. Some background.
- 2. What JFPatch-as-a-service is.
- 3. How it works.
- 4. What powers it.
- 5. Conclusions.



March 2019



Who am I?

- A RISC OS architect and engineer, who's been away from the community for about 15 years.
- I used to do a lot of things with RISC OS, which you can read about on my site if you're interested gerph.org/riscos
- I'm not going to talk about that past here.
- I would like to think that I probably know RISC OS in design and execution better than anyone.



Dear gosh, why?

- What do I want to do with RISC OS and why?
 - Let's make something for me, because I can.



So, you want to use RISC OS, but...

- Development on RISC OS is tedious
 - The tools aren't great but they only run on RISC OS... and I don't have a RISC OS system (other than RPCEmu)
- RISC OS testing is awful
 - Most RISC OS projects do ad-hoc testing, rely on users; no automation
- RISC OS is awful for testing
 - If something goes wrong, you need to hard reboot; no isolation; no security



How does the real world do things?

- Source control!
- Cross compiling
- Managed development environments
- Automated testing of changes
- Feature and regression testing
- Fleets of systems available for use



How can I do this? (1)

Source control:

• Move things to Git, because CVS is so very painful.

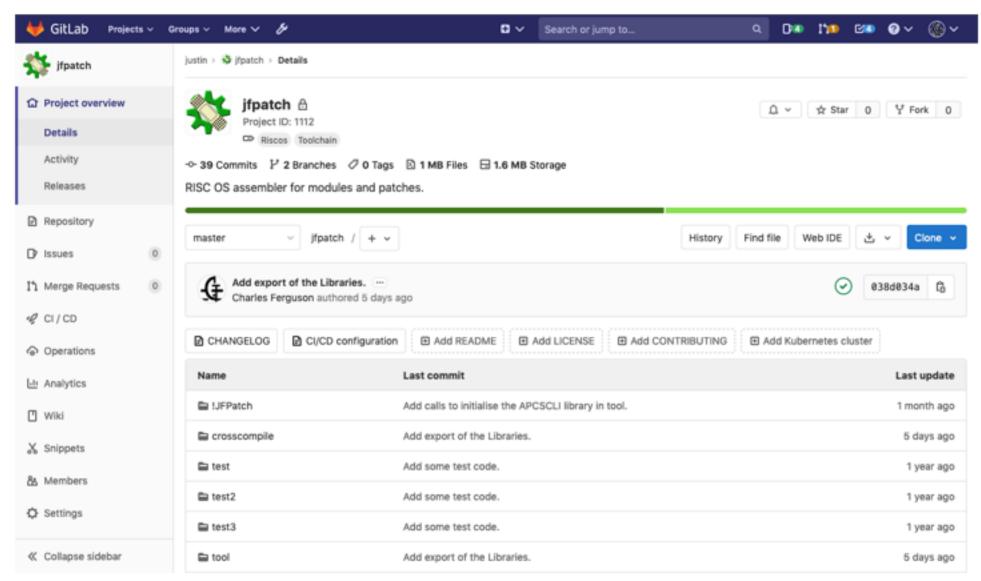


How can I do this? (1)

Source control:

• Move things to Git, because CVS is so very painful.

Tech: GitLab, running on my linux server - it's publicly accessible, but most of the 1000-odd projects are private.





How can I do this? (2)

Cross compiling:



How can I do this? (2)

Cross compiling:

Already had the toolchain ported to 32bit Linux and Windows, back in 2005.

Tech: Port the toolchain to 64bit Linux and 64bit macOS.

```
charles@laputa ~/pro/RO/mod/ris/Sou/Des/TaskWindow (master)> rm o*/*; riscos-amu
BUILD32=1 ram
riscos-objasm -Stamp -quit -I@ -predefine "BUILD RAM SETL {TRUE}" -apcs
3/32/fpe2/swst/fp -predefine "BUILD ZM SETL {TRUE}" -predefine "No26bitCode SETL {TRUE}"
-predefine "No32bitCode SETL {FALSE}" -predefine "APCS SETS \"APCS-32\"" -o oz32/Taskman
s/Taskman
ARM AOF Macro Assembler 3.32 (JRF:3.32.38) [07 Mar 2006]
Unrecognised APCS qualifier /fpe2
Unrecognised APCS qualifier /fp
MyDomain = 0000058C
Deprecated form of PSR field specifier used (use _cxsf)
riscos-link -rmf -rescan -C++ -o rm32/TaskWindow,ffa oz32.Taskman
TaskWindow: Module built {RAM}
```

How can I do this? (2)

Cross compiling:

• Already had the toolchain ported to 32bit Linux and Windows, back in 2005.

Tech: Port the toolchain to 64bit Linux and 64bit macOS.

Tech: Tool to extract example code from 'Rosetta Code' for testing (https://github.com/gerph/rosettacode)



How can I do this? (3)

Managed environments:

• How do I get my toolchain? find my libraries? store built components?

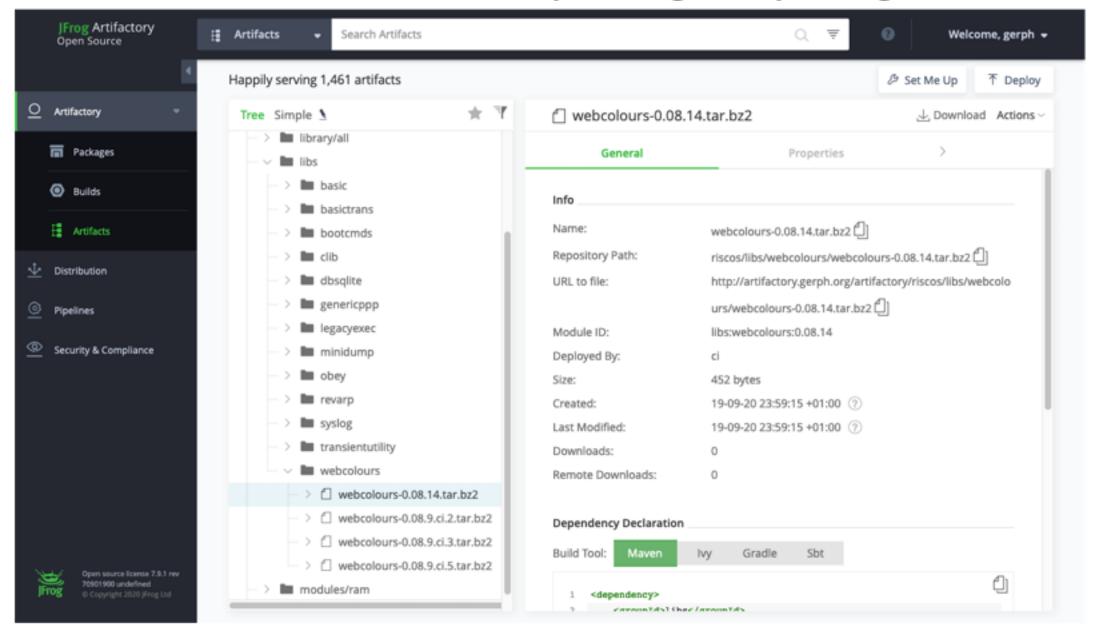


How can I do this? (3)

Managed environments:

• How do I get my toolchain? find my libraries? store built components?

Tech: Artifactory for artifacts, and created some tools for pushing and pulling resources.





How can I do this? (4)

Managed environments: (cont'd)

• What if I don't want to download my toolchain all the time?



How can I do this? (4)

Managed environments: (cont'd)

What if I don't want to download my toolchain all the time?

Tech: Docker RISC OS development environment.

```
charles@laputa ~/pro/RO/mod/ris/Sou/Des/WindowScroll (master)>
docker run -it --rm -v $PWD:/riscos-source -v $PWD/build:/riscos-build --workdir /riscos-source
gerph/riscos-build riscos-amu
riscos-cmunge -px -DCMHG -IC:, RISC OSLib: -26bit -o oz/modhead cmhg/modhead
CMunge 0.77 (JRF:0.77.47) [13 Jun 2006]
Copyright (c) 1999-2006 Robin Watts/Justin Fletcher
Norcroft RISC OS ARM C vsn 5.18 (JRF:5.18.119) [Jun 7 2020]
ARM AOF Macro Assembler 3.32 (JRF:3.32.38) [07 Mar 2006]
0 Errors, 2 Warnings suppressed by -NOWarn
riscos-cc -c -Wc -fa -IC:, RISC OSLib: -za1 -apcs 3/26/fpe2/swst/fp -D CONFIG=26 -zM -zps1
-o oz/main c/main
Norcroft RISC OS ARM C vsn 5.18 (JRF:5.18.119) [Jun 7 2020]
"c/main", line 564: Warning: '=': cast of 'int' to differing enum
c/main: 1 warning, 0 errors, 0 serious errors
riscos-link -rmf -rescan -C++ -o rm/WindowScroll, ffa oz.main oz.modhead C:o.stubs
```

How can I do this? (5)

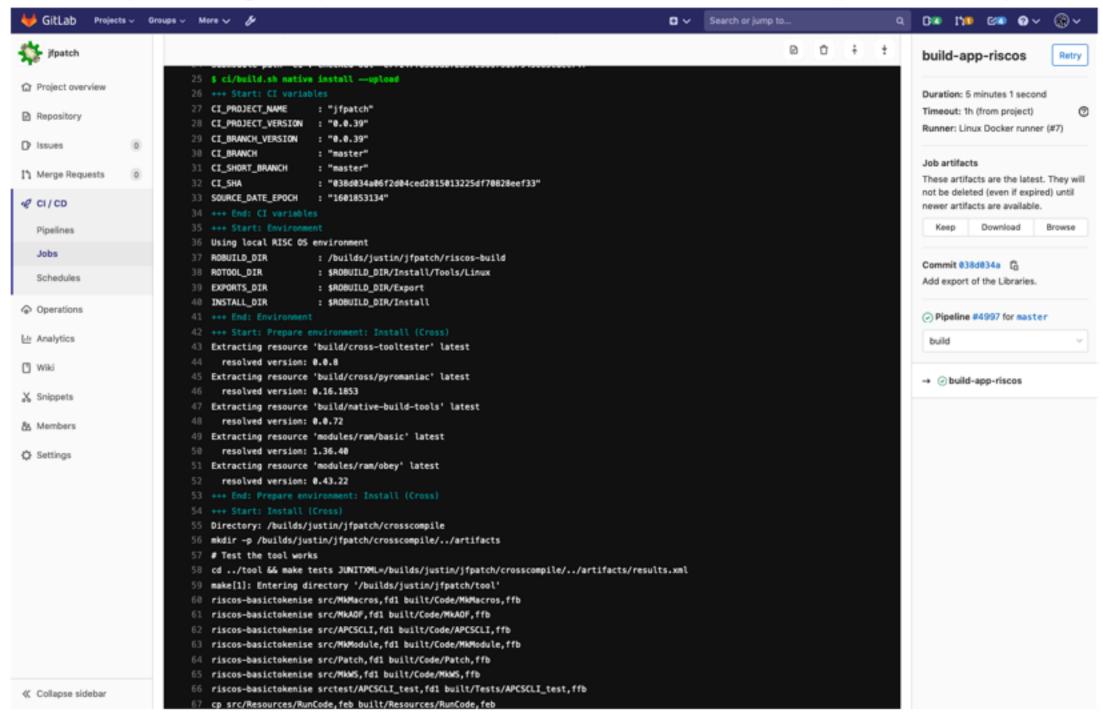
Automated testing:



How can I do this? (5)

Automated testing:

Tech: GitLab CI triggers on every change - pulls resources from Artifactory, builds, pushes result to Artifactory.





How can I do this? (6)

Feature and regression testing:

• Build programs and test code on other platforms.



How can I do this? (6)

Feature and regression testing:

- Build programs and test code on other platforms.
- I need a way to test things on RISC OS, too...

Tech: ... we'll come to that later ...



How can I do this? (7)

Fleets of systems for people to use:

• That seems a stretch, but maybe it's not so hard...

Tech: JFPatch-as-a-service begins that process



March 2020



Why?

A friend said to me...

"I can't wait until you csa.announce this and confuse the bejesus out of the RISC OS civilians."

To which my answer was...

"JFPatch as a service would be a doddle to do right now. A service that nobody asked for, or needed."



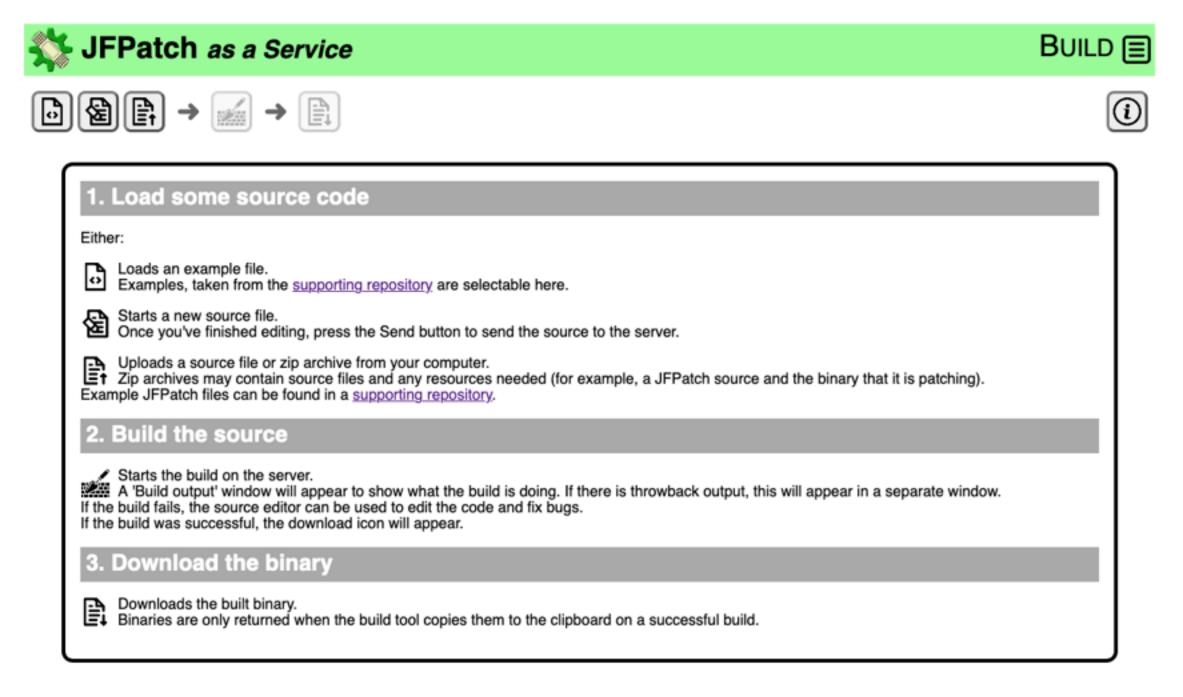
What is JFPatch?

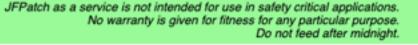
- It's a pre-processor for the BASIC assembler.
- It has its own file format which describes things to patch, or modules to build.
- It converts these to BASIC files, then runs the BASIC, which does the heavy lifting of assembling.
- It is, itself, written in BASIC.
- It was used to write many of my early assembler modules.



What is the service?

Takes its inspiration from Matt Godbolt's Compiler explorer - https://godbolt.org/







What can you build with the service? (1)

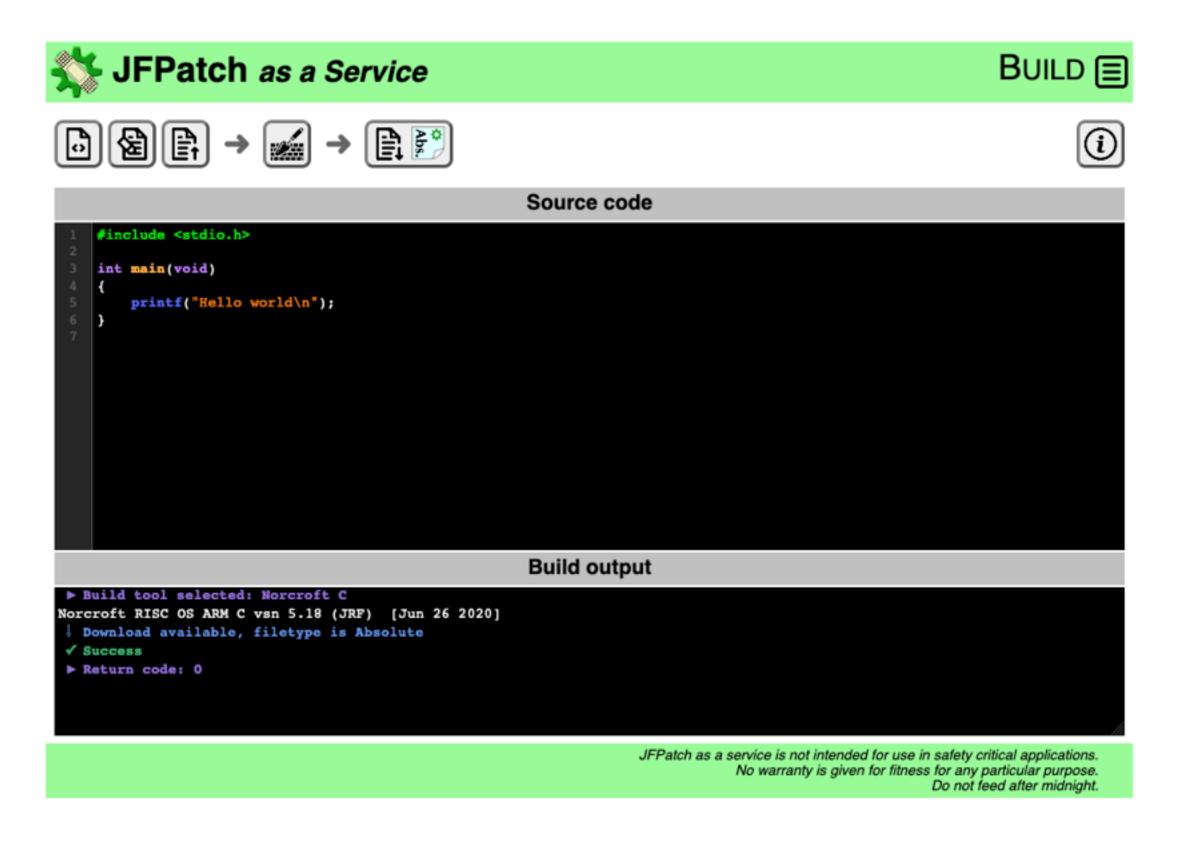
- Any JFPatch code (now builds 32bit code)
- C code that compiles with the Norcroft compiler
- Pascal code (which will be converted to C and compiled with the Norcroft compiler)
- Perl code
- BASIC assembler
- Objasm assembler.

Tech: All the toolchain is built for 32bit RISC OS, automatically taken from Artifactory when the service is built.



What can you build with the service? (2)

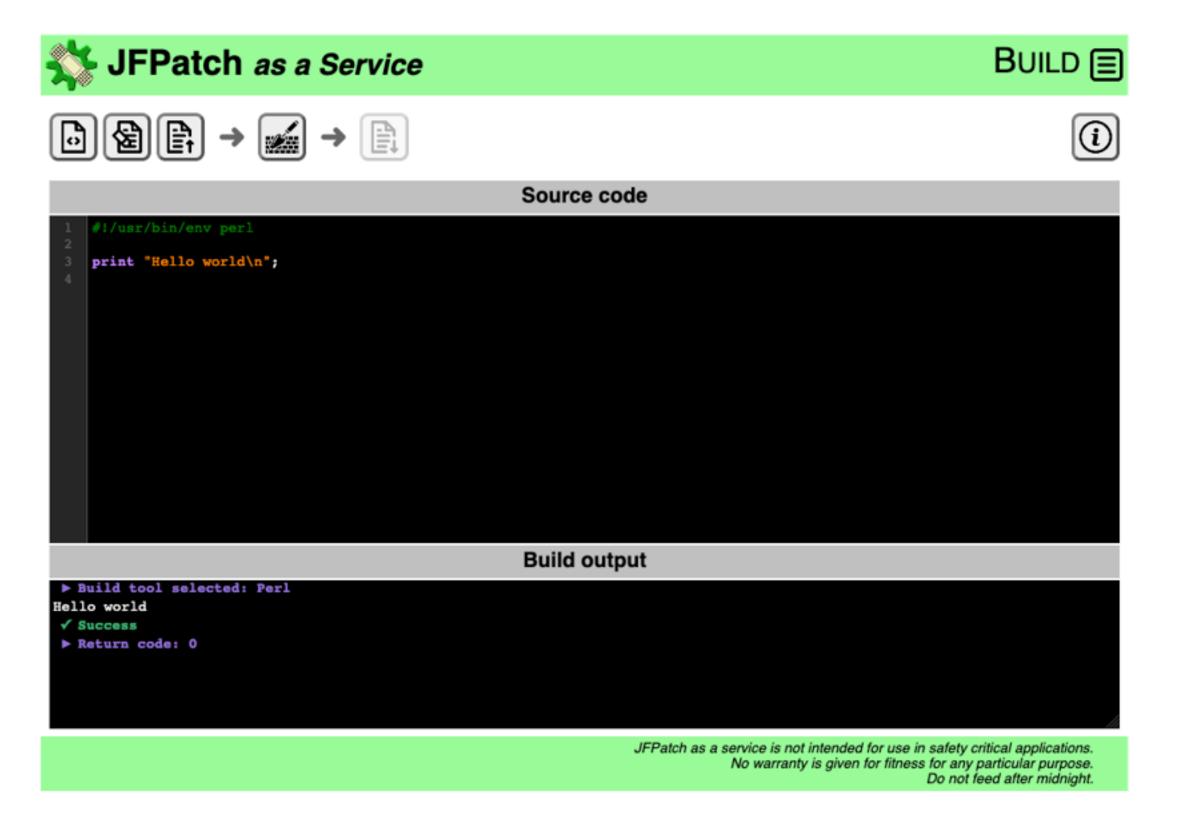
C code...





What can you build with the service? (3)

Perl code...





What can you build with the service? (4)

Plain BASIC...





What might use the service?

Automated builds can use this:

- LineEditor (BASIC assembler) https://github.com/philpem/LineEditor
- Nettle (C application) https://github.com/gerph/Nettle/tree/ci
- CObey (C module) https://github.com/gerph/cobey
- ErrorCancel (ObjAsm) https://github.com/gerph/errorcancel
- Pico (C command line tool) https://github.com/gerph/pico
- DDEUtilsJF (JFPatch module) https://github.com/gerph/ddeutilsjf



How do you use the service?

Two interfaces, which are documented:

- JSON API.
- WebSockets API.

Documented on the website: https://jfpatch.riscos.online/api.html

Examples can be found at: https://github.com/gerph/jfpatch-as-a-service-examples



How do you use the JSON API?

Use your favourite HTTP request library. For example, cur1:

```
curl -i -F 'source=@source-file' http://jfpatch.riscos.online/build/json
```

Get a JSON response:

```
"data": "... data goes here ...",
"filetype": 4092,
"messages": [
  "Build tool selected: JFPatch",
  "Return code: 0"
],
"output": [
  "JFPatch ARM assembler v2.56\u00df (02 Mar 2020) [Justin Fletcher]\r\n",
  "Pre-processing...\r\n",
  "Assembling...\r\n"
],
"rc": 0,
"throwback": []
```

How do you use the WebSockets API?

Using the wsclient.py example gives a similar output.

```
welcome: u'Linking over Internet with RISCOS Pyromaniac Agent version 1.04'
response: u'Source loaded'
response: u'Started build'
message: u'Build tool selected: JFPatch'
output: u'JFPatch ARM assembler v2.56\xdf (02 Mar 2020) [Justin Fletcher]\r\n'
output: u'Pre-processing...\r\n'
output: u'Assembling...\r\n'
clipboard: {u'filetype': 4092, u'data': u'... data goes here ...'}
rc: 0
message: u'Return code: 0'
complete: True
```

Q: What about when you don't have, or can't use, Python?

A: robuild-client handles that.



What is the robuild-client?

- Created a build client that can be used to do the heavy work.
- Can be found at https://github.com/gerph/robuild-client
- Builds for Linux...



JFPatch-as-a-Service

What is the robuild-client?

- Created a build client that can be used to do the heavy work.
- Can be found at https://github.com/gerph/robuild-client
- Builds for Linux...
- ... then uses the tool it built to submit its code to the service, to build the RISC OS version.

Tech:

- robuild-client.
- port of JSON parse/creation library.
- WebSockets library.



JFPatch-as-a-Service

How does the service know what to do?

- Simple files are recognised by their format.
- Zip files are recognised by their content.
 - The .robuild.yaml file can control what is actually run.



JFPatch-as-a-Service

How does the service know what to do?

- Simple files are recognised by their format.
- Zip files are recognised by their content.
 - The .robuild.yaml file can control what is actually run.

```
%YAML 1.0
---

jobs:
build:
    # Env defines system variables which will be used within the environment.
    # Multiple variables may be assigned.
env:
    "Sys$Environment": ROBuild

# Commands which should be executed to perform the build.
# The build will terminate if any command returns a non-0 return code or an error.
script:
    - dir riscos
    - !BuildAll
    - Clipboard_FromFile client.aif32.riscos-build-online
```

March 2020



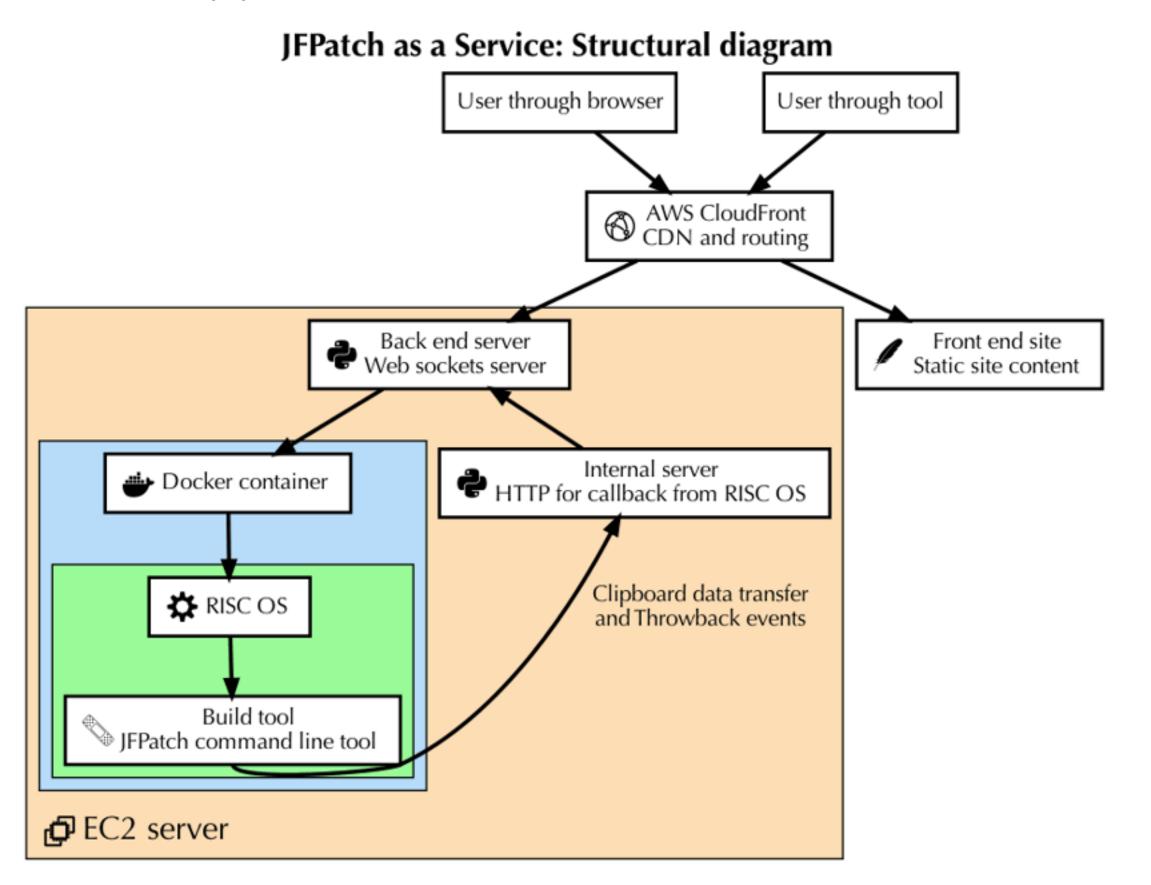
What is the service made of? (1)

Tech:

- Infrastructure AWS SSL, routing and linux server.
- Front End Static site, websockets to talk to back end
 - Custom CodeMirror colouring https://github.com/gerph/CodeMirror/tree/riscos-modes
- Back End Python REST JSON API and WebSockets service
 - RISC OS Zip file decoding in Python https://github.com/gerph/python-zipinfo-riscos
- Tools JFPatch tool, compiler, assembler, linker, amu, etc.



What is the service made of? (2)



What runs those services? (1)

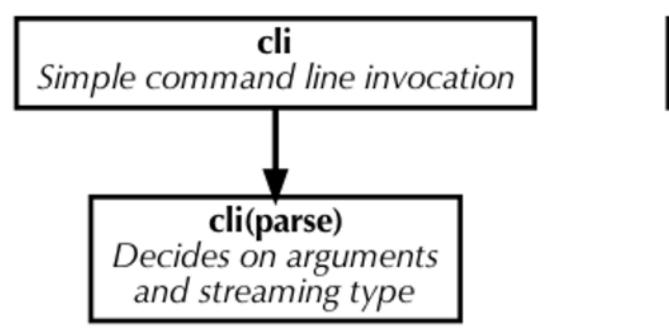
JFPatch as a Service: Interface control flow

server JSON HTTP API server cli Simple command line invocation wsserver WebSockets API server

What runs those services? (2)

JFPatch as a Service: Interface control flow

server JSON HTTP API server



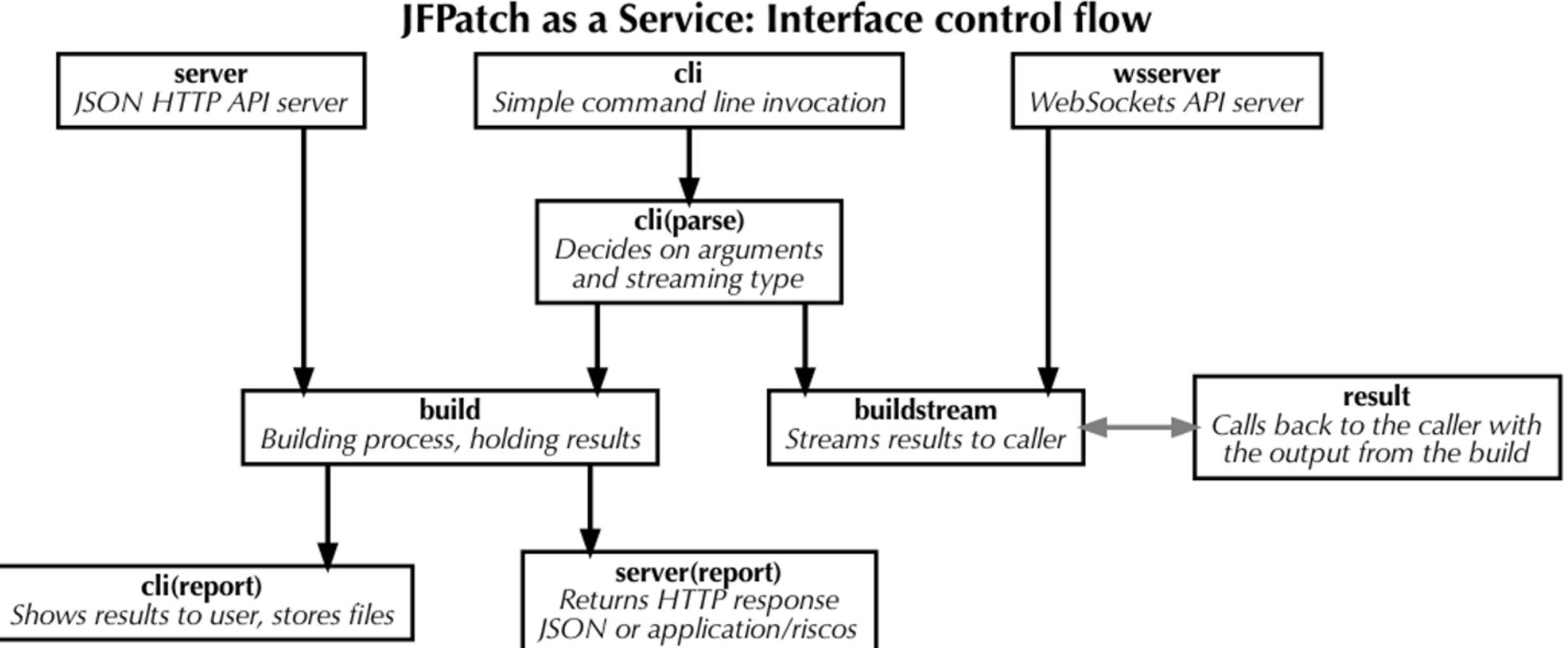
WebSockets API server

wsserver

What runs those services? (3)

JFPatch as a Service: Interface control flow server wsserver Simple command line invocation JSON HTTP API server WebSockets API server cli(parse) Decides on arguments and streaming type result buildstream build Calls back to the caller with Building process, holding results Streams results to caller the output from the build

What runs those services? (4)



What runs those services? (5)

JFPatch as a Service: Builder control flow

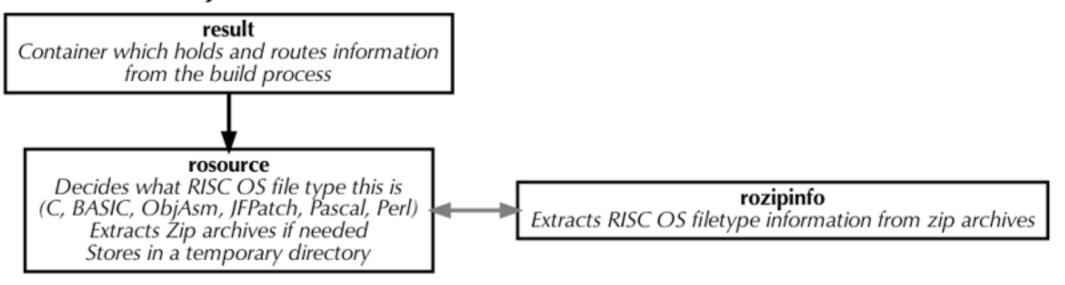
result

Container which holds and routes information from the build process



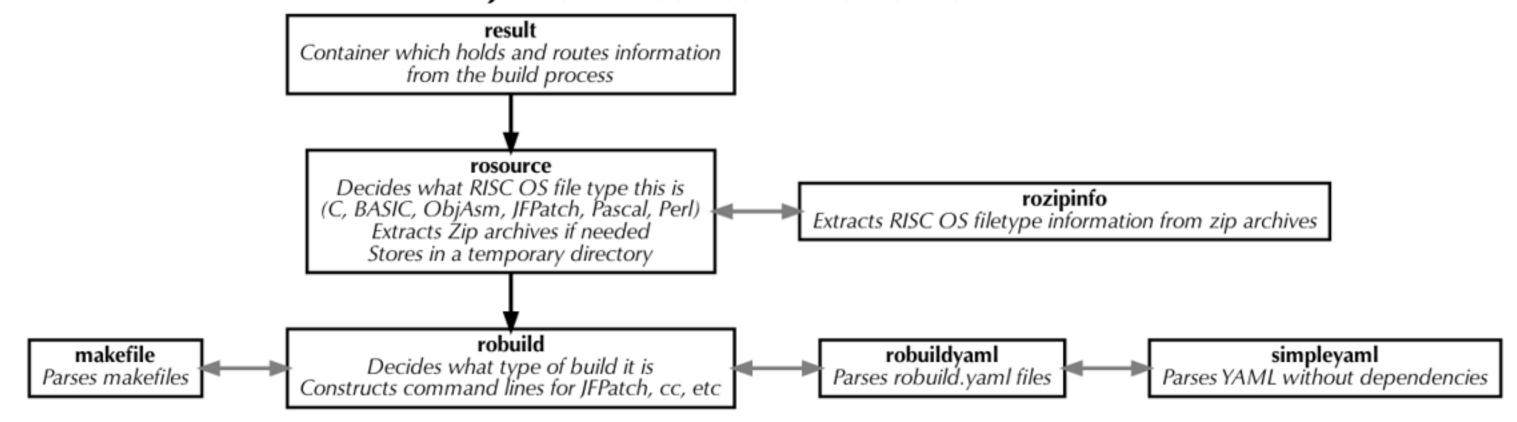
What runs those services? (6)

JFPatch as a Service: Builder control flow



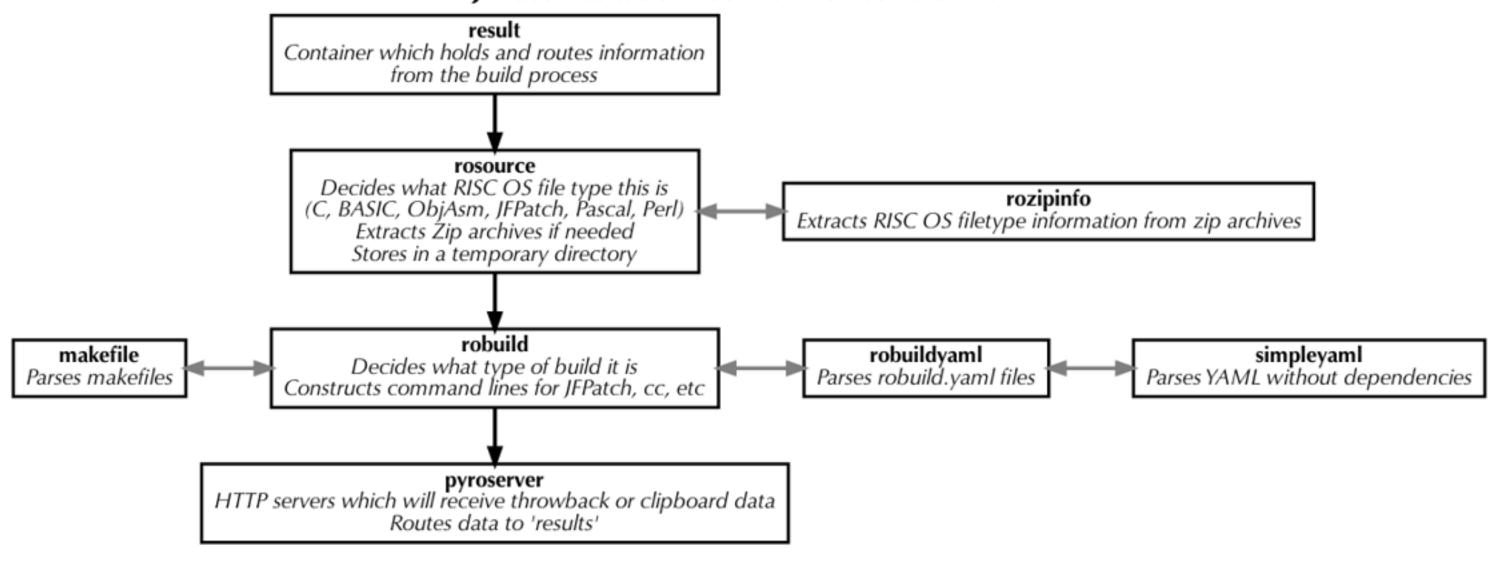
What runs those services? (7)

JFPatch as a Service: Builder control flow



What runs those services? (8)

JFPatch as a Service: Builder control flow



What runs those services? (9)

JFPatch as a Service: Builder control flow result Container which holds and routes information from the build process rosource Decides what RISC OS file type this is rozipinfo (C, BASIC, ObjAsm, JFPatch, Pascal, Perl) Extracts Zip archives if needed Extracts RISC OS filetype information from zip archives Stores in a temporary directory robuild simpleyaml Parses YAML without dependencies makefile robuildyaml Decides what type of build it is Constructs command lines for JFPatch, cc, etc Parses robuild.yaml files Parses makefiles **pyroserver** HTTP servers which will receive throwback or clipboard data Routes data to 'results' docker **pyro** Constructs command lines Manages running docker containers Streams data to 'results' to run inside docker streamedinput Streams process output in a separate thread

What runs those services? (10)

- robuild has worked out the RISC OS commands to use.
- pyro is given those commands and constructs a command that can run RISC OS with those commands.
- docker is given that command, and builds a command to run RISC OS within a docker container.
- ... and the results of all of that gets fed back to the results object, which passes it back to the caller.



Wait what?

"Wait, RISC OS is running in Docker?
But Docker runs on Linux?
You're running RISC OS on Linux then?"



• • •

June 2019



June 2019



How do you test RISC OS software without RISC OS?

- My RiscPC is in storage.
- It's not good for testing.



How do you test RISC OS software without RISC OS?

- My RiscPC is in storage.
- It's not good for testing.
- RISC OS was originally run semi-hosted from a BBC, using the BBC as the I/O and RISC OS as the main computer.
- That's what I want to be able to do I want to be able to drive RISC OS from the CLI of a sane machine.



Surely that's easy? (1)

• Surely that's easy? You just run an emulation system until it hits a SWI... ... and then you make the SWI do the I/O thing. Then you run some more?

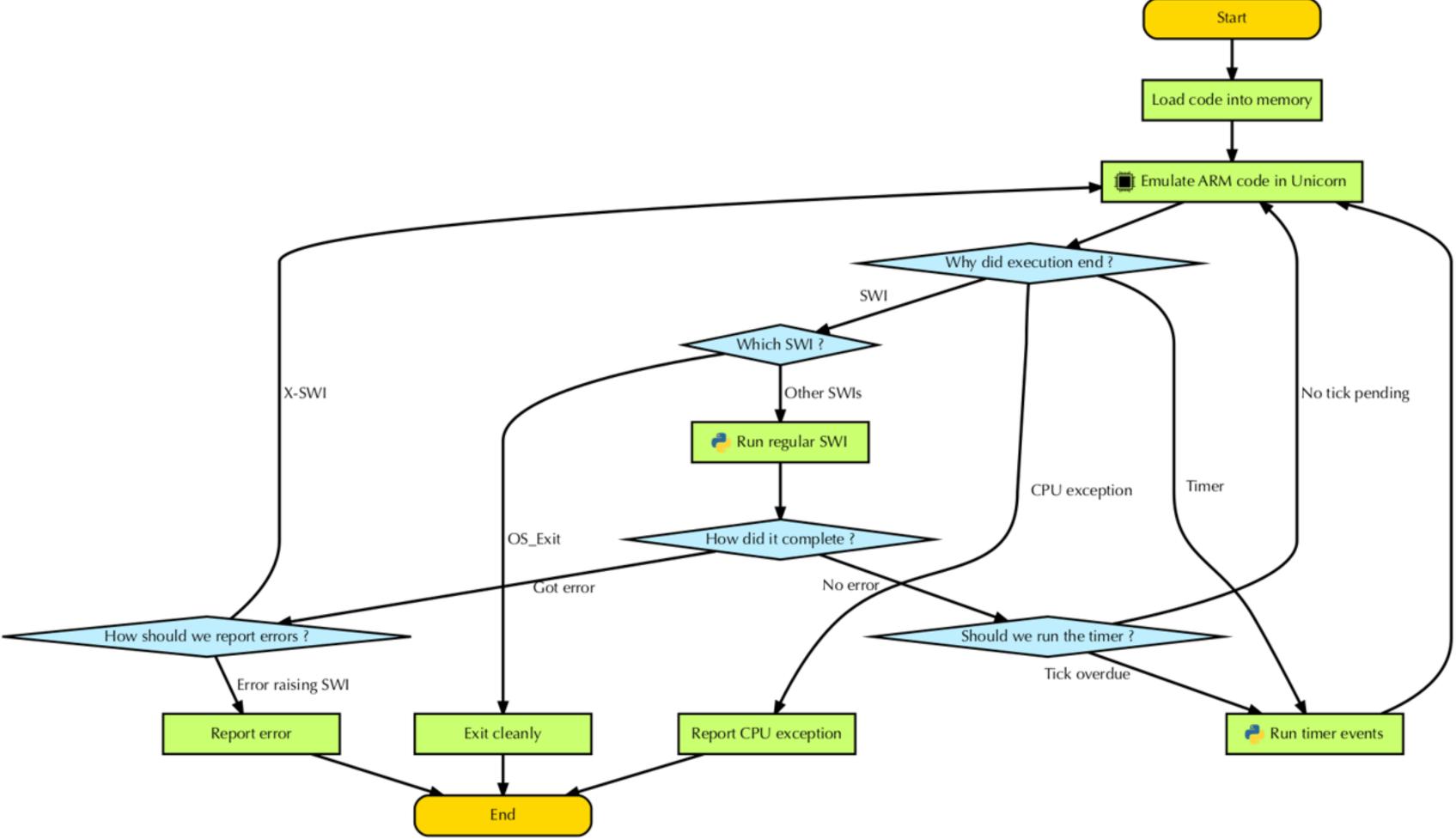


Surely that's easy? (1)

- Surely that's easy? You just run an emulation system until it hits a SWI... ... and then you make the SWI do the I/O thing. Then you run some more?
- Yes that's exactly what you do.
- The IfThere tool ran on June 10th not well, but it ran.



Pyromaniac: Basic execution





What is RISC OS Pyromaniac?

- Pyromaniac is an alternative implementation of RISC OS for non-ARM systems.
- It is intended for use as a testing and prototyping environment which may be used during development and automated testing.
- Written in a high level language to make that possible.



What's in a name?

- Pyromaniac is the system that runs ARM code.
- RISC OS is what's implemented on top of that.

So...

- A name to distinguish it from the ARM implementation.
 - RISC OS Pyromaniac
- A name for the ARM implementations.
 - RISC OS Classic

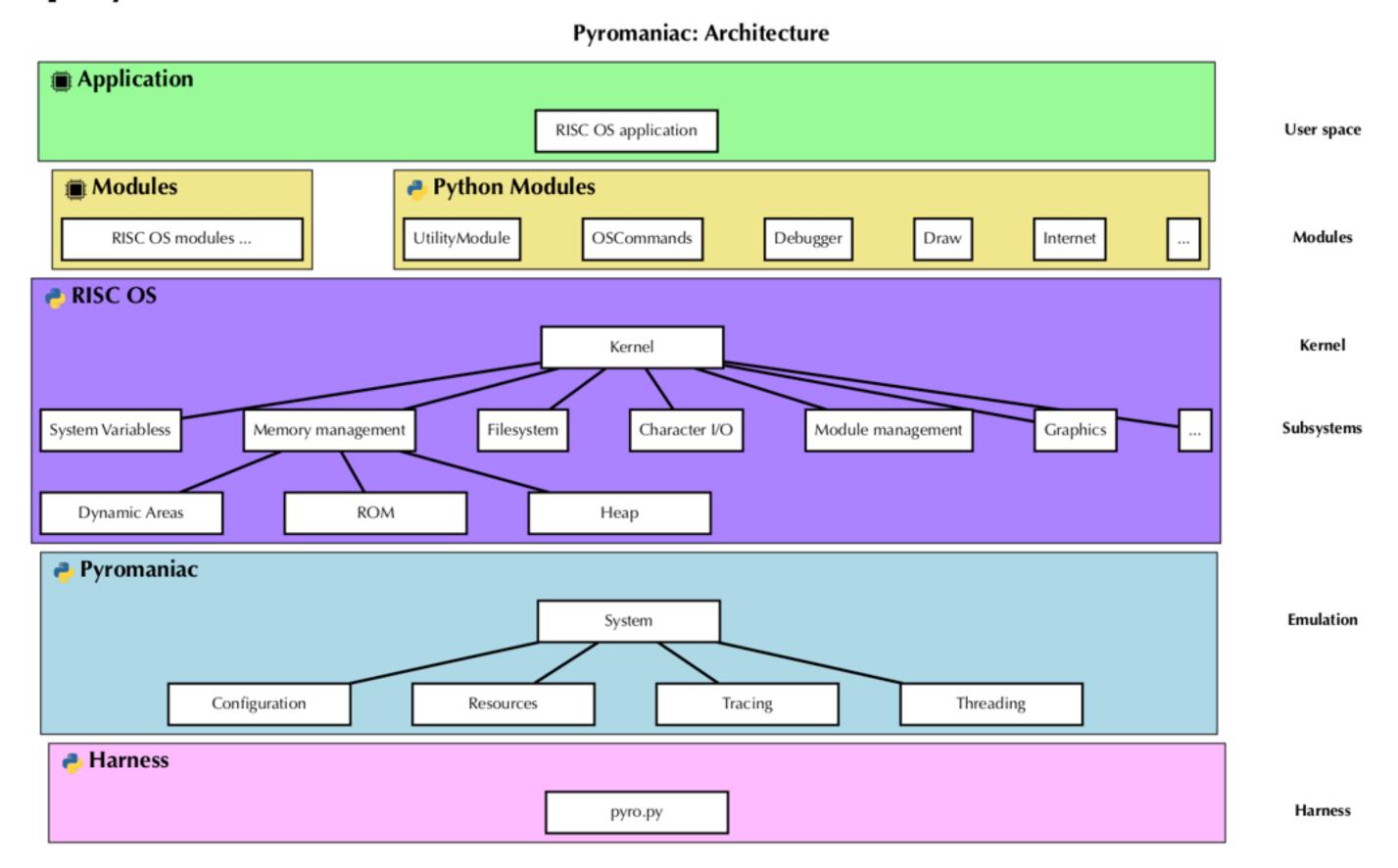


What makes up Pyromaniac? (1)

- Written in Python.
- Uses Unicorn (a QEmu derived package) for emulating 32bit ARM code.
- All other packages are optional.
 - Disassembly needs capstone.
 - Graphics needs python-cairo.
 - UI needs wxpython or gtk+3.
 - Networking more featured with netifaces.
 - Clipboard interaction with system with pyperclip.
 - Sound needs python-rtmidi.



What makes up Pyromaniac? (2)



How is it different from other systems?

RISC OS emulation:

- RPCEmu, ArcEm Hardware emulators.
- Riscose OS interface replacement.
- Amethyst ARM unit testing tool.
- Linux Port Hardware / interface replacement.

Other systems:

- Wine OS interface replacement.
- Docker System isolation.
- Rosetta Dynamic recompilation.



How does it compare to a bare Operating System?

Has many of the same things:

- Address space management; memory allocation.
- System calls from applications.
- Heap management.
- I/O management.
- Device drivers.

But some are missing:

- Page table management.
- Hardware interrupts.
- Memory mapped devices.



What does it mean?

- A command line only version of RISC OS.
- A RISC OS which runs 32bit ARM binaries, on Windows, macOS, or Linux.
- A reimplementation, which uses none of the code that went before.
- Focused on being able to test software and diagnose issues more easily.



What does it mean?

- A command line only version of RISC OS.
- A RISC OS which runs 32bit ARM binaries, on Windows, macOS, or Linux.
- A reimplementation, which uses none of the code that went before.
- Focused on being able to test software and diagnose issues more easily.

Tech: RISC OS Pyromaniac, able to run RISC OS programs on other systems!



Command line only?

- Command line is the primary interface.
- Graphics implementations exist either 'headless' or using a window showing the screen but command line is where it excels.
- For testing, you largely want to be able to exercise things without UI interactions, at least for the lower level tests.



No graphics, then?

Different parts of the system:

- VDU VDU4, text output.
- Graphics VDU5, OS_Plot, Draw, Font.
- Frame buffer Bitmap of the screen.
- UI How you see the VDU and Graphics systems.



No graphics, then?

Different parts of the system:

- VDU VDU4, text output: Well supported
- Graphics VDU5, OS_Plot, Draw, Font.
- Frame buffer Bitmap of the screen.
- UI How you see the VDU and Graphics systems.



No graphics, then?

Different parts of the system:

- VDU VDU4, text output: Well supported
- Graphics VDU5, OS_Plot, Draw, Font: Well supported, but no sprites
- Frame buffer Bitmap of the screen.
- UI How you see the VDU and Graphics systems.



No graphics, then?

Different parts of the system:

- VDU VDU4, text output: Well supported
- Graphics VDU5, OS_Plot, Draw, Font: Well supported, but no sprites
- Frame buffer Bitmap of the screen: **Nope**
- UI How you see the VDU and Graphics systems.



No graphics, then?

Different parts of the system:

- VDU VDU4, text output: Well supported
- Graphics VDU5, OS_Plot, Draw, Font: Well supported, but no sprites
- Frame buffer Bitmap of the screen: **Nope**
- UI How you see the VDU and Graphics systems: wxWidgets and GTK



No graphics, then?

Different parts of the system:

- VDU VDU4, text output: Well supported
- Graphics VDU5, OS_Plot, Draw, Font: Well supported, but no sprites
- Frame buffer Bitmap of the screen: Nope
- UI How you see the VDU and Graphics systems: wxWidgets and GTK

What works...

- The VDU system, and the graphics system work, mostly.
- VDU and graphics are complex so not everything works as it does in RISC OS Classic.
- Not all of it works as documented after all not all of it is documented!



How do you use it? (1)

Command line invocation:

```
charles@laputa ~/pyromaniac> ./pyro.py --load-internal-modules --command 'gos'
Supervisor

*fx0

Error: RISC OS 7.16 (03 Oct 2020) [Pyromaniac 0.16 on Darwin/x86_64] (Error number &f7)
*time
Fri,09 Oct 2020 23:00:04
*quit
charles@laputa ~/pyromaniac>
```



How do you use it? (2)

Running RISC OS programs:

```
charles@laputa ~/pyromaniac> echo '10PRINT "Hello world"' > myprog,fd1
charles@laputa ~/pyromaniac> ./pyro.py --load-internal-modules --load-module
modules/BASIC,ffa --command myprog
Hello world
charles@laputa ~/pyromaniac>
```



Graphics demo!



Graphics demo!

Graphics features:

- Fonts.
- DrawFiles.
- Images.
- Screen bank flipping.
- Mouse pointer.

Others:

Key input



Graphics demo! (presentation)

Tech:

- Slide presentation system.
- Markdown parser.
- FontMap for font remappings.
- WebColours module for colour parsing.
- ImageFileRender for general image rendering, using DrawFile for vectors.



Features - What works?

- System Runs 32bit modules, utilities and applications.
- Interaction Interacts with the host as its primary interface
- Video Pretty good VDU and graphics support GTK/WxWidgets, or snapshots of state.
- Sound SoundChannels mapped through MIDI
- Filesystem Host filesystem by default, using ,xxx filename convention.
- Network Internet module provides limited support for IPv4 and IPv6 networking.
- Compatibility Many simple programs work, if their support modules are loaded.



Features - What doesn't work?

- Desktop Not supported
- Filesystems No registration of filesystems
- Sound No wave output
- Graphics No frame buffer, No Sprites, No true colour modes
- Many other things



Networking

- Internet module supplied, using host interfaces.
 - Supports af_inet, af_inet6, af_unix.
 - Many ioctls are supported, mapped to the host system.
- Resolver module provides IPv4 host name resolution
- EtherPyromaniac provides a DCI4 driver.
 - Provides a virtual network.
- EasySockets, which bypasses Internet.

Tech: Tap-Tun JSON server for Ethernet frames.



Draw module (1)

- Draw module supplied.
- Can render through the Cairo path system.
- Classic DrawFile works the 'Gerph' logo is a Drawfile.
- Classic Draw module can be used too.



Draw module (2)





FontManager

- FontManager module supplied.
- Can uses Cairo 'toy' fonts.
 - Can be configured to use any 'fontconfig' discovered fonts.
- Supports different alphabets, including UTF-8.

But also

- Classic FontManager works...
- ... if you disable bitmap generation it just uses Draw.



Configuration

- RISC OS Pyromaniac is highly configurable over 240 directly configurable options, in 59 groups.
- Configuration can be on the command line or in configuration files.
- Example:
 - ./pyro.py --config modules.rominit_noisy=true --load-internal-modules --command gos
 - ./pyro.py --config memorymap.rom_base=90000000 --load-internal-modules --command modules



Configuration files

```
%YAML 1.1
# Configuration for loading the ROM for RISC OS 5
debug:
  - modules
  - traceregionfunc
  - podules
  - swimisuse
config:
  podule.extensionrom1: ROMs/riscos5
 modules.rominit_noisy: true
 memorymap.rom_base: 0x8800000
 modules.unplug: extrom1:Podule,ParallelDeviceDriver,TaskWindow,SpriteExtend,SystemDevices,...
modules:
  internal: true
```



Tracing and debugging

- Trace features:
 - Report all instructions.
 - Report basic block execution, function entries.
 - Report SWI entry and exit conditions.
 - Function, memory and SWI traps.
 - Exception and API misuse reports.
- Debug features:
 - Most modules have debug available.
 - Can be enabled at runtime (*PyromaniacDebug +<option>).



Tracing code (1)

Tracing SWI arguments (--debug traceswiargs):

Tech: OSLib parser and templating system



Tracing code (2)

```
$ pyro testcode/bin/word_time_string --debug trace
              r1, &07000174
700013c: ADR
                                         ; -> [&0000000, &0000000,
                                             &00000000, &00000000]
7000140: MOV
              r0, #&e
                                          ; #14
7000144: MOV
              r2, #0
7000148: STRB
              r2, [r1]
                                         ; R2 = \&000000000, R1 = \&07000174
700014c: SWI
              OS Word
7000150: SWI
              OS_WriteS
7000164: MOV
              r0, r1
                                         ; R1 = \&07000174
             OS Write0
7000168: SWI
700016c: SWI
              OS_NewLine
Time string: Sun,06 Sep 2020 08:22:38
7000170: MOV
                                         ; R14 = &04107fe0
              pc, lr
4107fe0: SWI
              &FEED05
```



Debugging

```
charles@laputa ~/demo> pyro --load-internal-modules --command gos --debug cli,clialias,osfscontrol
CLI: 'gos'
CLI alias: Wildcard 'Alias$gos' start read from None
Supervisor
*.
CLI: '.'
CLI alias: '.' expansion
CLI alias: Expanded to 'Cat '
CLI alias: Execute: Cat
CLI: 'Cat '
CLI alias: Wildcard 'Alias$Cat' start read from None
Catalogue directory '@'
Canonicalise filename '@' using pathvar OL, path OL
Read boot option of '$'
Dir. $ Option 02 (run)
Read directory 0
CSD NoFileSystem: $too
Read directory 3
Lib. NoFileSystem:$
Read directory 2
URD NoFileSystem:$
example/py WR/WR
                      example/pyc WR/WR
                                            wimperror
                                                        WR/WR
```

What is it like to work with? (1)

- The Pyromaniac context is usually ro, containing...
 - registers (ro.regs[#])
 - memory (ro.memory[address])
 - configuration (ro.config['group.option'])
 - resource (ro.resource['resource'])
 - methods for execution (ro.execute, ro.execute_with_error)
 - trace functions (ro.trace)
 - the kernel (ro.kernel)
- The Pyromaniac layer is all about the lower level execution and setup of the system.



What is it like to work with? (2)

- The RISC OS Kernel context is ro.kernel...
 - dynamic areas (ro.kernel.da, ro.kernel.da_rma.ro.kernel.da_appspace, ...)
 - vectors (ro.kernel.vectors[#])
 - modules (ro.kernel.modules)
 - vdu and graphics system (ro.kernel.vdu, ro.kernel.graphics)
 - input and mouse (ro.kernel.input, ro.kernel.mouse)
 - filesystem (ro.kernel.filesystem)
 - system variables (ro.kernel.sysvars[varname])
 - program environment (ro.kernel.progenv)
 - system APIs (ro.kernel.api)
- The Kernel object is always referenced explicitly from ro.



What is it like to work with? (3)

```
11 11 11
OS_ReadEscapeState implementation.
.....
from riscos import handlers
import riscos.constants.swis as swis
@handlers.swi.register(swis.OS ReadEscapeState)
def swi_OS_ReadEscapeState(ro, swin, regs):
    11 11 11
    OS ReadEscapeState
    <= C flag is set if an escape condition has occurred
    11 11 11
    regs.cpsr c = ro.kernel.progenv.escape condition
```



What is it like to work with? (4)

Many commands are just a thin wrapper around a system call:

```
def cmd_rmload(self, args):
    """
    Syntax: *RMLoad <module-file> [<args>]
    """
    self.ro.kernel.api.os_module(modhand.ModHandReason_Load, args)
```



What is it like to work with? (5)

Context handlers can be used to make memory allocation easy:



What is it like to work with? (6)

Context handlers can also preserve the output state:

```
def cmd_show(self, args):
    Syntax: *Show [<variable>]
    # Preserve and enable VDU paging
    with self.ro.kernel.api.vdupaging():
        # Enumerate and print variables
        for varname, vartype, value in self.ro.kernel.api.os_readvarval_enumerate(args):
            if vartype in (sysvars.TYPE_STRING, sysvars.TYPE_MACRO):
                # String returned parameters should have their value escaped GSTrans style
                value = self.ro.kernel.gstrans.escape(value,
                                                   escape_chars='|"<' if vartype != sysvars.TYPE_MACRO else '',
                                                   escape control=True,
                                                   escape topbit=True)
            suffix = ''
            if vartype == sysvars.TYPE NUMBER:
                suffix = '(number)'
            elif vartype == sysvars.TYPE MACRO:
                suffix = '(macro)'
            self.ro.kernel.writeln('%s%s : %s' % (varname, suffix, value))
```

What is it like to work with? (7)

Exceptions can be trapped in a pythonic way:

```
def cmd_unset(self, args):
    """
    Syntax: *Unset <variable>
    """
    try:
        self.ro.kernel.api.os_setvarval_delete(args)
    except RISCOSError as exc:
        if exc.errnum != errors.ErrorNumber_VarCantFind:
            raise
        # Lack of a variable is not an error
```



What good is it? (1)

- Writing my own software.
 - This presentation tool.
 - Other older components.
- Trying things out.
 - Sound system.
- Debugging other people's software!
 - https://asciinema.org/a/345766 shows an interactive session demonstrating that freeing the stack you're currently using may have bad effects.



What good is it? (2)

```
Supervisor
*cobey:obey echosed
==== Begin exception report ====
Exception triggered: Exception 'Prefetch Abort'
  r0 = &a9a9a9a9, r1 = &a9a9a9a9, r2 = &000000000, r3 = &a9a9a9a9
  r4 = &00000191, r5 = &07001f28, r6 = &07008ac0, r7 = &00000001
  r8 = &07008aa8, r9 = &07007720, r10 = &07008d18, r11 = &a9a9a9a9
  r12 = &a9a9a9a9, sp = &a9a9a9a9, lr = &a9a9a9a9, pc = &a9a9a9ac
  CPSR= &60000010 : USR-32 ARM fi ae qvCZn
Recently executed code:
   ---- Block &07006f4c, 1 instructions ----
    7006f4c: LDR
                    pc, &07007230
                                              ; = &0382095c
   ---- Block &0382095c, 5 instructions ----
    382095c: {DA 'ROM', module 'SharedCLibrary'}
   Function: memset
    382095c: MOV
                    r12, sp
                                              ; Function: memset
    3820960: PUSH
                   {r0, r11, r12, lr, pc}
                    r11, r12, #4
     3820964: SUB
                    r2, r2, #4
    3820968: SUBS
    382096c: BMI
                     &038209E4
    ---- Block &038209a0, 4 instructions repeated 229 times ----
    38209a0: STMIA r0!, {r1, r3, r12, lr}
    38209a4: STMIA r0!, {r1, r3, r12, lr}
    38209a8: SUBS r2, r2, #&20
                     &038209A0
    38209ac: BGE
   ---- Block &038209d4, 6 instructions ----
    38209d4: SUBS r2, r2, #4
    38209d8: STRLT r1, [r0], #4
    38209dc: STMGEIA r0!, {r1, r3}
    38209e0: SUBGE r2, r2, #4
    38209e4: ADDS r2, r2, #4
    38209e8: LDMDBEQ rll, {r0, rll, sp, pc}
==== End exception report ====
Error: Internal error: Abort on instruction fetch at &a9a9a9a8 (Error number &80000001)
```

Problems...

- IRQs and timed events aren't handled well.
- Execution context is split between emulated system and Python code.
- Error handling is still a bit troublesome.
- Replaced writing device driver, with writing interface modules.



Other technologies!

Tech:

- RISC OS Alphabets in Python Codecs https://github.com/gerph/python-codecs-riscos
- Non-RISC OS editor syntax modes:
 - SublimeText syntax for RISC OS command files https://github.com/gerph/sublimetext-riscoscommand-syntax
 - NanoRC syntaxes for some RISC OS file types https://github.com/gerph/nanorc-riscos
- Tool for building hourglass modules https://github.com/gerph/riscos-hourglass-maker
- Tests for RISC OS APIs, and a tool for testing tools https://github.com/gerph/riscos-tests
- PRM-in-XML documentation system rework.
- Miscellaneous toolchain updates.
- Changelog management system https://gitlab.gerph.org/gerph/changelog-management



What does it run on?

- macOS (console, GTK, wxWidgets)
 - Also a dedicated application.
- Linux (console, GTK, wxWidgets)
 - Also within a docker container.
- Windows (console, wxWidgets) [native and under Wine, also docker wine-py]
 - Also a dedicated application.

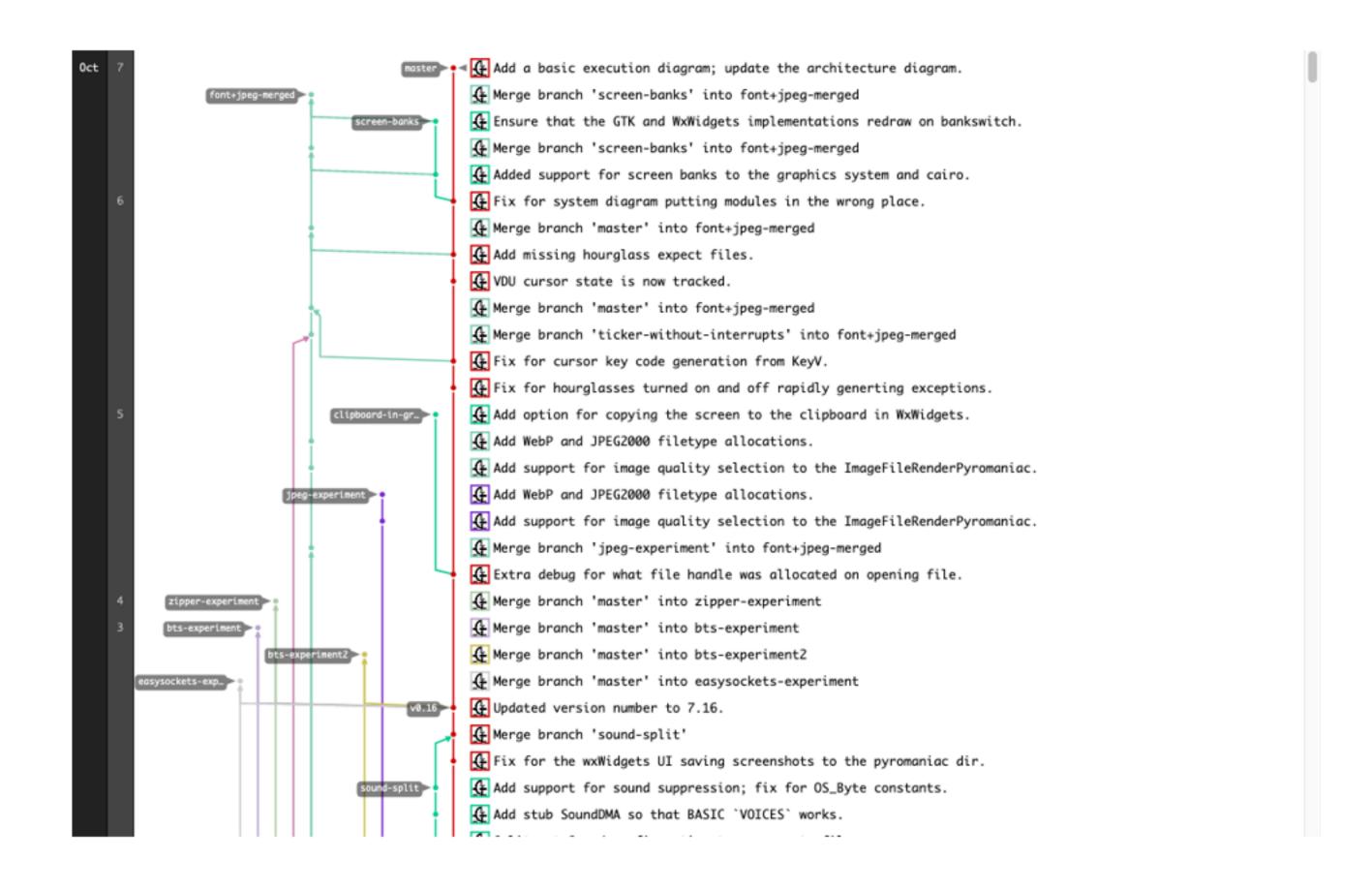


"Releases"?

- Released once a month, just to myself.
 - October's version is 0.16.
 - Releases are a way to stop it being unusably 'half finished'.
 - Releases are a great incentive I really have achieved a lot this month!
- Long lived development, for example...
 - Font Manager lived on a branch for about 6 months.
 - EasySockets is still on a branch.
 - PyromaniacGit is still be worked on.



"Releases"?





5. Conclusion



Conclusion

Have I done what I set out to do?

Let's review what I saw as problems...

- Development on RISC OS is tedious
- RISC OS testing is awful
- RISC OS is awful for testing



- Source control
- Cross compiling
- Managed development environments
- Automated testing
- Feature and regression testing
- Fleets of systems available



- Source control yup, using GitLab, PyromaniacGit
- Cross compiling
- Managed development environments
- Automated testing
- Feature and regression testing
- Fleets of systems available



- Source control yup, using GitLab, PyromaniacGit
- Cross compiling *yup, Linux and macOS*
- Managed development environments
- Automated testing
- Feature and regression testing
- Fleets of systems available



- Source control yup, using GitLab, PyromaniacGit
- Cross compiling yup, Linux and macOS
- Managed development environments yup, docker, artifactory, applications
- Automated testing
- Feature and regression testing
- Fleets of systems available



- Source control yup, using GitLab, PyromaniacGit
- Cross compiling yup, Linux and macOS
- Managed development environments yup, docker, artifactory, applications
- Automated testing yup, build.riscos.online, and GitHub and GitLab builds
- Feature and regression testing
- Fleets of systems available



- Source control yup, using GitLab, PyromaniacGit
- Cross compiling yup, Linux and macOS
- Managed development environments yup, docker, artifactory, applications
- Automated testing yup, build.riscos.online, and GitHub and GitLab builds
- Feature and regression testing yup, thousands of tests, some public
- Fleets of systems available



- Source control yup, using GitLab, PyromaniacGit
- Cross compiling yup, Linux and macOS
- Managed development environments yup, docker, artifactory, applications
- Automated testing yup, build.riscos.online, and GitHub and GitLab builds
- Feature and regression testing yup, tests for the OS, and code coverage
- Fleets of systems available well, no, not yet



RISC OS Testing is awful

- RISC OS Pyromaniac has tests about a thousand at present.
- Tests take about 18 minutes to run and run on Linux and macOS in parallel.
- Code coverage hovers at around 65%.



RISC OS is awful for testing

- Clarification: RISC OS Classic is awful for testing.
- Heavily used as part of the development of the present tool.
- JFPatch itself is tested.
- BASIC module has some tests that run programs.



Could it be better?

- More APIs.
- Better handling of corner cases.
- Sprites (sigh).
- Back Trace Structures.
- Finish the pending branches Windows, Zipper, EasySockets, Git, DCI4, ...
- Using it for actual testing that was what it was for!
- So many other opportunities.



References

If you're wanting to know more, or review this talk, a site, https://pyromaniac.riscos.online/ has been created which contains support materials:

- Copies of these slides.
- Links to the technologies in these slides.
- Explanations of the CI examples.
- Development images and screenshots.
- Documentation from Pyromaniac (features, changelogs, configuration info).

There's also a demonstration site: http://shell.riscos.online/.



Am I happy?

You can make whatever judgements you like!



6. Questions

Info site: https://pyromaniac.riscos.online/

Shell: http://shell.riscos.online/

